Scanning the distance to observations. Have 1 cameras looking at 100 boards. 10 Range-to-chessboards = 0.40Range-to-chessboards = 1.77Range-to-chessboards = 3.14Range-to-chessboards = 4.51Range-to-chessboards = 5.89Expected worst-direction uncertainty (pixels) 8 Range-to-chessboards = 7.26Range-to-chessboards = 8.63Range-to-chessboards = 10.002 10 20 30 50 60 70 80 40 90 100

Range (m)