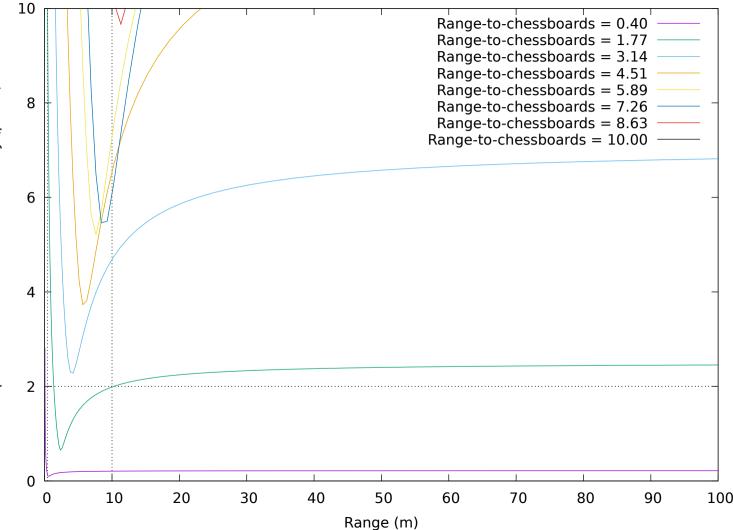
Scanning the distance to observations. Have 1 cameras looking at 100 boards.



Expected worst-direction uncertainty (pixels)